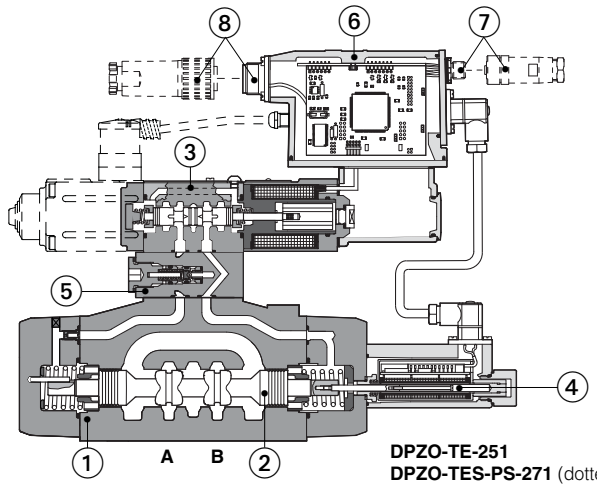
Proportional directional valves type DPZO-T*

two stage, with position transducer, ISO 4401 sizes 10, 16 and 25



DPZO-TE-251
DPZO-TES-PS-271 (dotted line)

① Valve body
② Main stage Spool
③ Pilot valve
④ Main stage position transducer
⑤ Pressure reducing valve
⑥ Integral electronics
⑦ Communication connector
⑧ Main connector

DPZO-T* are two stage proportional valves with position transducer on the main spool which provide both directional and non compensated flow control according to electronic reference signal.

They operate in association with electronic drivers, see section 2, which supply the proportional valves with proper current to align valve regulation to the reference signal supplied to the electronic driver.

They are available in different executions:
- -T, with position transducers ④;
- -TE, -TES as -T plus analog (TE) or digital (TES) integral electronics ⑥.

The 4-way spool ②, sliding into a 5-chambers body ①, is piloted by a proportional directional valve ③ type DHZO (see tab. F160) and it is controlled in closed loop position by means of the LVDT transducer ④.
The pressure reducing valve ⑤ with fixed setting ensures a costant piloting pressure.
The integral electronics ⑥ ensures factory presetting, fine functionality plus valve-to-valve interchangeability and simplified wiring and installation.
The electronic main connector ⑧ is fully interchangeable for –TE and –TES executions.
Standard 7 pin main connector is used for power supply, analog input reference and monitor signals.
12 pin connector is used for options /Z and /S*.
The special /S* options add a closed loop control of pressure (/SP) or force (/SF and /SL) to the basic closed loop spool position one.

Following communication interfaces ⑦ are available for the digital -TES execution:
- -PS, Serial communication interface. The valve reference signal is provided with analogue commands
- -BC, CANopen interface
- -BP, PROFIBUS DP interface

The valves with -BC and -BP interfaces can be integrated into a fieldbus communication network and thus digitally operated by the machine control unit.

The coils are fully plastic encapsulated (insulation class H) and the valves have antivibration, antishock and weather-proof features.
Mounting surface: ISO 4401 sizes 10, 16 and 25.

Max flow respectively up to 160 l/min, 340 l/min and 680 l/min with valve differential pressure Δp = 30 bar, see table 2.

Max pressure: 350 bar.

1 MODEL CODE

**DPZO –TES – PS – 2 7 1 – L 5 / * / ** / *

Piloted proportional directional valve

T = with position transducer
TE = as T plus integral analog electronics
TES = as T plus integral digital electronics

Communication interfaces (only for TES)
PS = RS232 serial
BC = CANbus
BP = PROFIBUS-DP

Valve size: **1** = 10; **2** = 16; **3** = 25

Configuration, see section 3
5 = external plus central position, spring centered
7 = 3 position, spring centered

Spool overlapping in central position, see section 3
1 = P, A, B, T with positive overlapping (1)
3 = P positive overlapping (1); A, B, T, negative overlapping

Spool type (regulating characteristics):
L = linear;
S = progressive;
D = differential-progressive (as **S**, but with P-A = Q, P-B = Q/2)
DL = differential-linear (as **L**, but with P-A = Q, P-B = Q/2)
Q = linear spool, for alternate P/Q controls (2)
V = differential-progressive, for alternate P/Q controls (2)

Spool size: **3, 5, 9** see section 3

Synthetic fluids
WG = water-glycol
PE = phosphate ester

Series number

Hydraulic options, see section 4:
B = solenoid, integral electronics and position transducer at side of port A of the main stage
E = external pilot (through port X)
D = internal drain

Electronic options for -TE execution see section 7:
F = fault signal
I = current reference input and monitor (4÷20 mA)
Q = enable signal
Z = enable, fault and monitor signal (12 pin connector)

Electronic options for -TES execution see section 9:
I = current reference input and monitor (4÷20 mA)
Z = double power supply, enable, fault and monitor signals (12 pin connector)

Special options for -TES execution see section 9:
SF = additional closed loop force control, with two remote pressure transducers
SL = additional closed loop force control with one remote load cell
SP = additional closed loop pressure control with one remote pressure transducer
C = current feedback interface for transducer(s) **only for options /SF, /SL, /SP**

Notes:
(1) Overlapping = 20% of spool stroke for type **S, D** and **Q**; 10% of spool stroke for type **L** and **DL**
(2) The spools type **Q** and **V** are used in combination with option /SP of digital integral drivers, see section 13.1 and G212

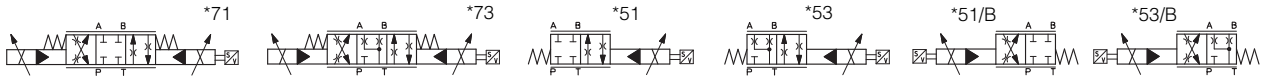
2 ELECTRONIC DRIVERS

Valve model	-T	-TE	-TES	-TES / SF, SL, SP
Drivers model	E-ME-T	E-RI-TE	E-RI-TES	E-RI-TES/SF, /SL, /SP
Data sheet	G140	G200	G210	G212

Note: For power supply and communication connector see section 16

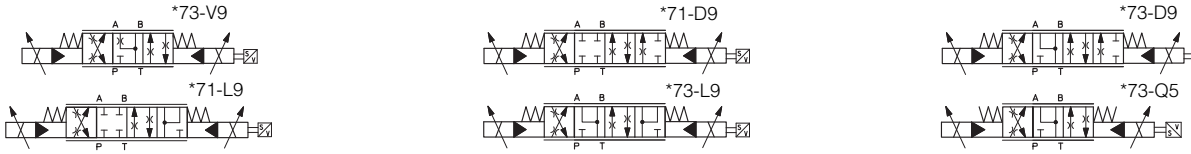
3 HYDRAULIC CHARACTERISTICS OF STANDARD SPOOL (based on mineral oil ISO VG 46 at 50 °C)

Standard spools - hydraulic symbols



Valve model	DPZO-T*-1				DPZO-T*-2							DPZO-T*-3			
Spool overlapping	1, 3				1, 3							1, 3			
Spool type and size	L5	S5	D5	DL5	L3	S3	D3	L5	S5	D5	DL5	L5	S5	D5	DL5
Max flow (1): [l/min]															
at Δp = 10 bar	100		100:60		130		130:80	200	180	180:130	200:145	390	360	360:220	390:240
at Δp = 30 bar	160		160:100		225		225:130	340	310	310:225	340:250	680	620	620:380	680:410
max permissible flow	180		180:100		550		550:300	760	640	640:460	680:500	1450	1390	1350:820	1350:880

Specific spools - hydraulic symbols



Valve model	DPZO-T*-1			DPZO-T*-2				DPZO-T*-3		
Spool overlapping	1, 3	3		1, 3		3		1, 3	3	
Spool type and size	D9	Q5	V9	D9	L9	Q5	V9	D9	Q5	V9
Max flow (1): [l/min]										
at Δp = 10 bar	100:60	100		200:150	200			390:240	390	
at Δp = 30 bar	160:100	160		340:250	340			680:410	680	
max permissible flow	180:100	180		680:500	680			1450:880	1450	

Pressure limits [bar]	ports P, A, B, X = 350; T = 250 (10 for option /D); Y = 10		
Response time [ms]	< 60	< 75	< 80
Hysteresis [%]		≤ 1%	
Repeatability	± 0,5%		
Thermal drift	zero point displacement < 1% at ΔT = 40°C		

Notes:
- Above performance data refer to valves coupled with Atos electronic drivers, see section 2.
- In case of long time shutdown of the hydraulic supply to the pilot valve, the driver has to be switched off to avoid its overheating.

(1) For different Δp, the max flow is in accordance to the diagrams in section 13.2

4 HYDRAULIC OPTIONS

4.1 Option /B Solenoid, integral electronics and position transducer at side of port A of the main stage.

4.2 Pilot and drain configuration -The pilot / drain configuration can be modified as shown in the table E080 section 12.

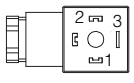
The valve's standard configuration provides internal pilot and external drain. For different pilot / drain configuration select:
Option /E External pilot (through port X). **Option /D** Internal drain.

5 GENERAL NOTES

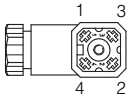
DPZO-T* proportional valves are CE marked according to the applicable Directives (e.g. Immunity/Emission EMC Directive and Low Voltage Directive).
Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in table F003 and in the installation notes supplied with relevant components.
The electrical signals of the valve (e.g. monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

6 CONNECTIONS FOR -T EXECUTION

SOLENOID POWER SUPPLY CONNECTOR	
PIN	Signal description
1	SUPPLY
2	SUPPLY
3	GND



POSITION TRANSDUCER CONNECTOR	
PIN	Signal description
1	OUTPUT SIGNAL
2	SUPPLY -15 VDC
3	SUPPLY +15 VDC
4	GND



7 ANALOG INTEGRAL DRIVERS -TE - OPTIONS

Standard driver execution provides on the 7 pin main connector:

Power supply - 24VDC must be appropriately stabilized or rectified and filtered; a 2,5 A safety fuse is required in series to the driver power supply
Apply at least a 10000 µF/40 V capacitance to single phase rectifiers or a 4700 µF/40 V capacitance to three phase rectifiers

Reference input signal - analog differential input with ±10 VDC nominal range (pin D,E), proportional to desired valve spool position

Monitor output signal - analog output signal proportional to the actual valve's spool position with ±10 VDC nominal range

Following options are available to adapt standard execution to special application requirements:

7.1 Option /F
It provides a Fault output signal in place of the Monitor output signal, to indicate fault conditions of the driver (cable interruption of spool transducers or reference signal - for /I option): Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC.

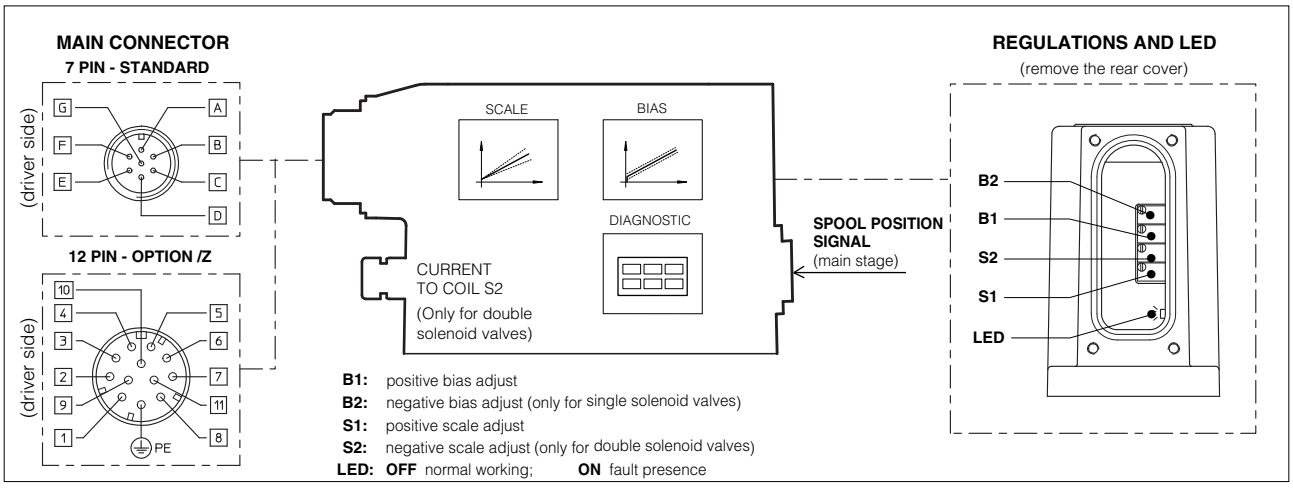
7.2 Option /I
It provides the 4÷20 mA current reference and monitor signals instead of the standard ±10 VDC
It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

7.3 Option /Q
It provides the possibility to enable or disable the valve functioning without cutting the power supply (the valve functioning is disabled but the driver current output stage is still active). To enable the driver supply a 24VDC on the enable input signal.

7.4 Option /Z
This option includes **/F** and **/Q** features, plus the Monitor output signal.
When the driver is disabled (0 VDC on Enable signal) Fault output is forced to 0 VDC.

7.5 Possible combined options: /FI and /IZ

8 ANALOG INTEGRAL DRIVERS -TE - MAIN FUNCTIONS AND ELECTRONIC CONNECTIONS



8.1 ELECTRONIC CONNECTIONS - 7 & 12 PIN MAIN CONNECTORS

Standard 7pin	/Z option 12pin	SIGNAL	TECHNICAL SPECIFICATIONS		NOTES
A	1	V+	Power supply 24 VDC for solenoid power stage and driver logic		Input - power supply
B	2	V0	Power supply 0 VDC for solenoid power stage and driver logic		Gnd - power supply
C (1)	7	AGND	Ground - signal zero for MONITOR signal	(for standard, /Z option)	Input - analog signal
	3	ENABLE	Enable (24 VDC) or disable (0 VDC) the driver	(for /Q and /Z options)	Input - on/off signal
D	4	INPUT+	Reference analog differential input: ±10 VDC maximum range For single solenoid valves the reference input is 0÷+10 VDC For double solenoid valves the reference input is ±10 VDC	(4 ÷ 20 mA for /I option) (4 ÷ 20 mA for /I option) (4 ÷ 20 mA for /I option)	Input - analog signal
E	5	INPUT -			
F (2)	6	MONITOR	Monitor analog output: ±10 VDC maximum range	(4 ÷ 20 mA for /I option)	Output - analog signal
	11	FAULT	Fault (0V) or normal working (24V)	(for /F and /Z option)	Output - on/off signal
-	8	R_ENABLE	Repeat Enable - output repetition of Enable input		Output - on/off signal
-	9	NC	do not connect		Output - on/off signal
-	10	NC	do not connect		Output - on/off signal
G	PE	EARTH	Internally connected to the driver housing		

Notes:

(1) with /Q option ENABLE signal replaces AGND on pin C; MONITOR signal is reffered to pin B

(2) with /F option FAULT signal replaces MONITOR on pin F.

- A minimum time of 50ms to 100ms have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero.

9 DIGITAL INTEGRAL DRIVERS -TES - OPTIONS

Standard driver execution provides on the 7 pin main connector:

Power supply - 24VDC must be appropriately stabilized or rectified and filtered; a 2,5 A safety fuse is required in series to each driver power supply Apply at least a 10000 µF/40 V capacitance to single phase rectifiers or a 4700 µF/40 V capacitance to three phase rectifiers

Reference input signal - analog differential input with ±10VDC nominal range (pin D,E), proportional to desired valve spool position

Monitor output signal - analog output signal proportional to the actual valve's spool position with ±10VDC nominal range

Following options are available to adapt standard execution to application requirements:

9.1 Option /I

It provides 4÷20 mA current reference and monitor signals instead of the standard ±10 V.

It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

9.2 Option /Z

It provides on a 12 pin main connector the above standard features plus:

Logic power supply

Option /Z provides separate power supply for the solenoid (pin 1, 2) and for the digital electronic circuits (pin 9, 10).
Cutting solenoid power supply allows to interrupt the valve functioning but keeping energized the digital electronics thus avoiding fault conditions of the machine fieldbus controller. This condition allows to realize safety systems in compliance with European Norms EN13849-1 (ex EN954-1).

Enable Input Signal

To enable the driver, supply a 24VDC on pin 3 referred to pin 2: when the Enable signal is set to zero the valve functioning is disabled (zero current to the solenoid) but the driver current output stage is still active. This condition does not comply with European Norms EN13849-1 (ex EN954-1).

Fault Output Signal

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4÷20mA input, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24VDC (pin 11 referred to pin 2): Fault status is not affected by the Enable input signal

9.3 Options /SP, /SF and /SL

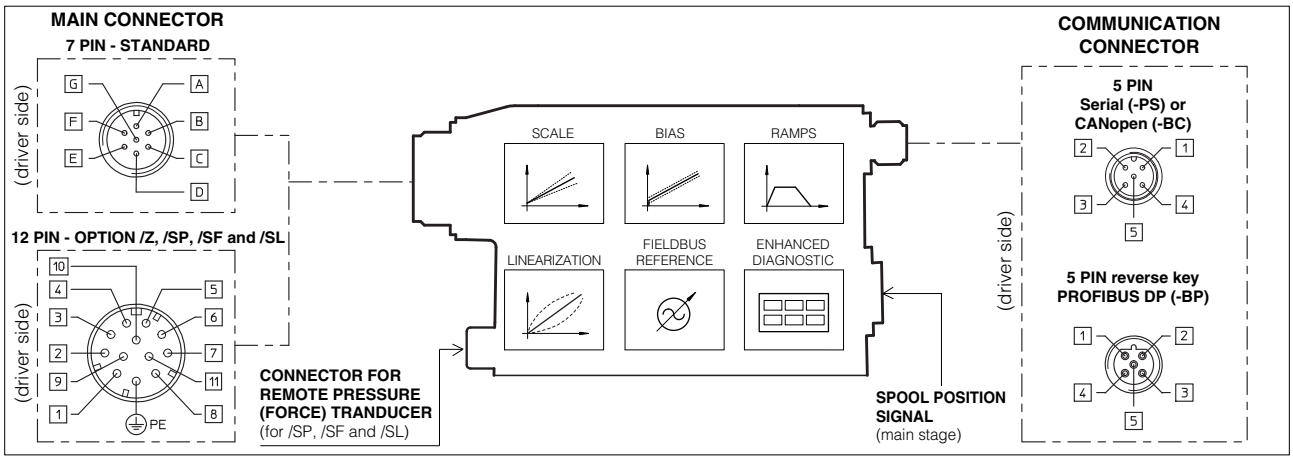
These options add the closed loop control of pressure (/SP) or force (/SF and /SL) to the basic functions of proportional directional valves: a dedicated software alternates pressure (force) and valve's spool position controls depending on the actual hydraulic system conditions.
A dedicated connector is available for the additional transducers that are required to be interfaced to the valve's driver (1 pressure transducer for /SP, 2 pressure transducers for /SF or 1 load cell for /SL).
Main 12 pin connector is the same as /Z option plus two analog signals specific for the pressure (force) control: one for reference (pin 7) and one for monitor (pin 8).
For futher details please refer to the driver technical table **G212.**

9.4 Options /C

Options /CSP, /CSF and /CSL are available to connect pressure (force) transducers with 4 ÷ 20mA current output signal.

9.5 Possible combined options: /ISF, /ISL, /ISP, /CSP, /CSF, /CSL, /CISP, /CISF, /CISL and /IZ

10 DIGITAL INTEGRAL DRIVERS -TES - MAIN FUNCTIONS AND ELECTRONIC CONNECTIONS



10.1 ELECTRONIC CONNECTIONS - 7 & 12 PIN MAIN CONNECTORS

Standard 7pin	/Z option 12pin	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
A	1	V+	Power supply 24 VDC for solenoid power stage (and for driver logic on 7 pin connection)	Input - power supply
B	2	V0	Power supply 0 VDC for solenoid power stage (and for driver logic on 7 pin connection)	Gnd - power supply
-	3	ENABLE	Enable (24 VDC) or disable (0 VDC) the driver	Input - on/off signal
D	4	INPUT+	Reference analog input: ±10 VDC maximum range (4 ÷ 20 mA for /I option) For single solenoid valves the reference input is 0÷+10 VDC (4 ÷ 20 mA for /I option) For double solenoid valves the reference input is ±10 VDC (4 ÷ 20 mA for /I option) standard: differential input; /Z option: common mode INPUT+ referred to AGND	Input - analog signal
E	-	INPUT -		
C	5	AGND	Ground - signal zero for MONITOR signal signal zero for INPUT+ signal (only for /Z option)	Gnd - analog signal
F	6	MONITOR	Monitor analog output: ±10 VDC maximum range (4 ÷ 20 mA for /I option)	Output - analog signal
-	7	NC	do not connect (pressure/force input for /SP, /SF and /SL options, see 9.3)	
-	8	NC	do not connect (pressure/force monitor for /SP, /SF and /SL options, see 9.3)	
-	9	VL+	Power supply 24 VDC for driver logic	Input - power supply
-	10	VL0	Power supply 0 VDC for driver logic	Gnd - power supply
-	11	FAULT	Fault (0V) or normal working (24V)	Output - on/off signal
G	PE	EARTH	Internally connected to the driver housing	

Note: A minimum time of 300 to 500 ms have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero.

10.2 ELECTRONIC CONNECTIONS - 5 PIN COMMUNICATION CONNECTORS

	-PS Serial		-BC CANopen		-BP PROFIBUS DP	
PIN	SIGNAL	TECHNICAL SPECIFICATION	SIGNAL	TECHNICAL SPECIFICATION	SIGNAL	TECHNICAL SPECIFICATION
1	NC	do not connect	CAN_SHLD	Shield	+5V	for termination
2	NC	do not connect	NC	do not connect	LINE-A	Bus line (high)
3	RS_GND	Signal zero data line	CAN_GND	Signal zero data line	DGND	data line and termination Signal zero
4	RS_RX	Valves receiving data line	CAN_H	Bus line (high)	LINE-B	Bus line (low)
5	RS_TX	Valves transmitting data line	CAN_L	Bus line (low)	SHIELD	

11 SOFTWARE TOOLS

The functional parameters of digital valves, as the bias, scale ramp and linearization of the regulation characteristic, can be easily set and optimized with the Atos E-SW programming software, available in three different versions according to the driver's communication interfacing: E-SW-PS (Serial), E-SW-BC (CANopen) and E-SW-BP (PROFIBUS DP).
A proper connection is required between the PC and the electronic driver communication port: for a more detailed description of software interface, PC requirements, adapters, cables and terminators, please **see table G500.**
Proportional valves with fieldbus communication interface (-BC and -BP) can be directly managed by the machine control unit; it is required to implement in the machine control the standard communication as described in the user manuals supplied with the relevant programming software. For detailed description of available fieldbus feature, **see table G510.**

On first supply of the E-SW software, it is required to apply for the registration in the Atos download area: **www.download.atos.com**
Once the registration is completed, the password will be sent by email.
The software remains active for 10 days from the installation date and then it stops until the user inputs his password.
With the password you can also download, in your personal area, the latest releases of the Atos software, manuals, drivers and configuration files.

12 MAIN CHARACTERISTICS OF PROPORTIONAL DIRECTIONAL VALVES

Assembly position	Any position
Subplate surface finishing	Roughness index, $\sqrt{}^{0,4}$ flatness ratio 0,01/100 (ISO 1101)
Ambient temperature	-20°C ÷ +70°C for -T execution; -20°C ÷ +60°C for -TE and -TES executions
Fluid	Hydraulic oil as per DIN 51524 ... 535 for other fluids see section 1
Recommended viscosity	15 ÷100 mm²/s at 40°C (ISO VG 15÷100)
Fluid contamination class	ISO 18/15 achieved with in line filters of 10 µm and $\beta_{10} \geq 75$ (recommended)
Fluid temperature	-20°C +60°C (standard and /WG seals) -20°C +80°C (/PE seals)
Coil resistance R at 20°C	3 ÷ 3,3 Ω
Max. solenoid current	2,6 A
Max. power	35 Watt
Insulation class	H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account
Protection degree (CEI EN-60529)	IP65 for -T execution; IP65÷67 for -TE and -TES executions, depending to the connector type (see sect. 16)
Duty factor	Continuous rating (ED=100%)

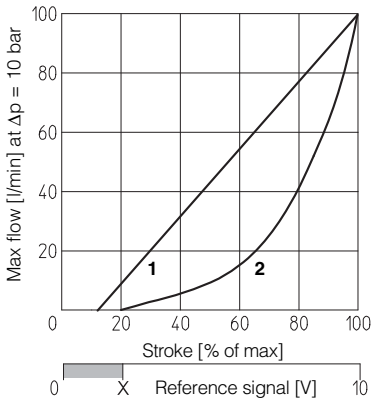
13 DIAGRAMS (based on mineral oil ISO VG 46 at 50 °C)

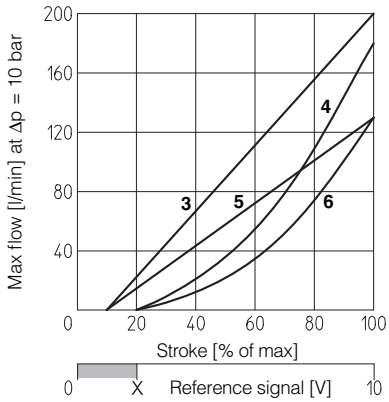
13.1 Regulation diagrams

DPZO-1:
1 = 1L5, 1DL5, 3L5, 3DL5
2 = 1S5, 1D5, 3S5, 3D5

DPZO-2:
3 = 1L5, 1DL5, 3L5, 3DL5
4 = 1S5, 1D5, 3S5, 3D5
5 = 1L3, 3L3
6 = 1S3, 1D3, 3S3, 3D3

DPZO-3:
7 = 1L5, 1DL5, 3L5, 3DL5
8 = 1S5, 1D5, 3S5, 3D5





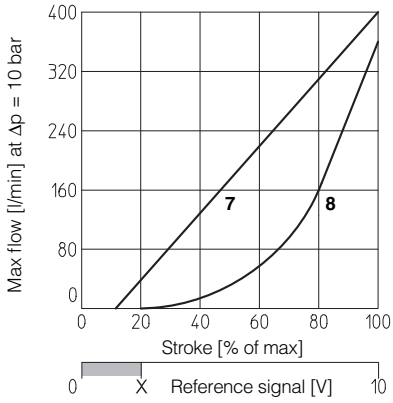
X = Threshold for bias activation depending to the valve type and amplifier type

Note:

Hydraulic configuration vs. reference signal:

Reference signal 0 ÷+10 V / 12÷20 mA P → A / B → T

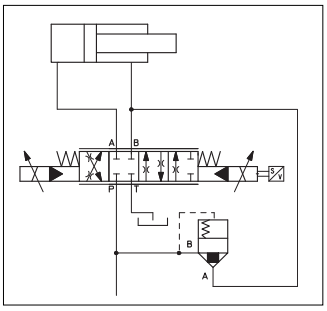
Reference signal 0 ÷-10 V / 4÷12 mA P → B / A → T



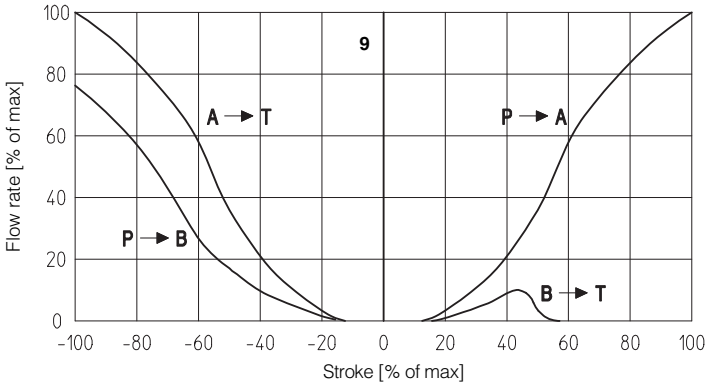
X = Threshold for bias activation depending to the valve type and amplifier type

9 = differential - regenerative spool D9

D9 spool type with a fourth position specific to regenerative circuit, performed by means of an additional external check valve.



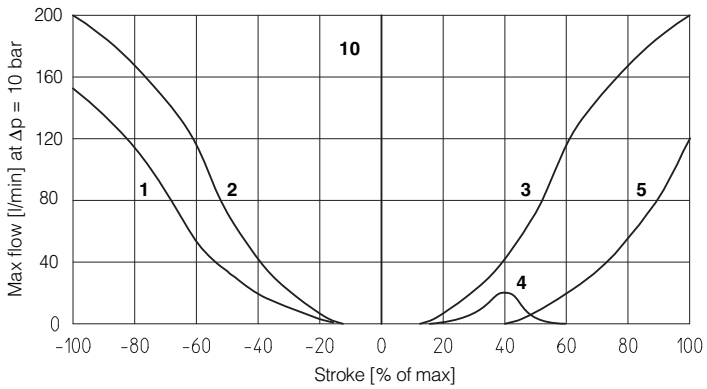
Application example



10 = linear - internal regenerative spool L9

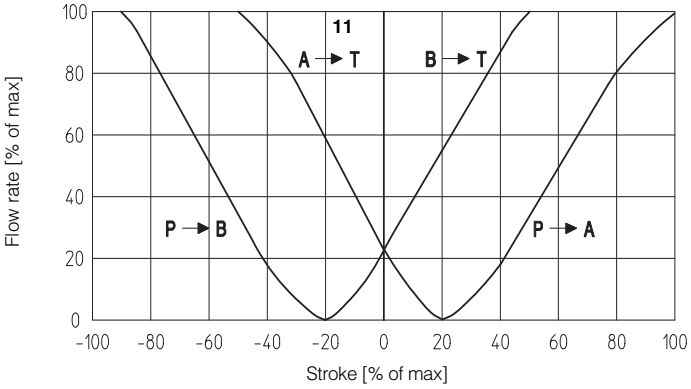
L9 spool type with a fourth position specific to regenerative circuit internal to the valve.

1 = P - B
2 = A - T
3 = P - A
4 = B - T
5 = P - B (regenerative)



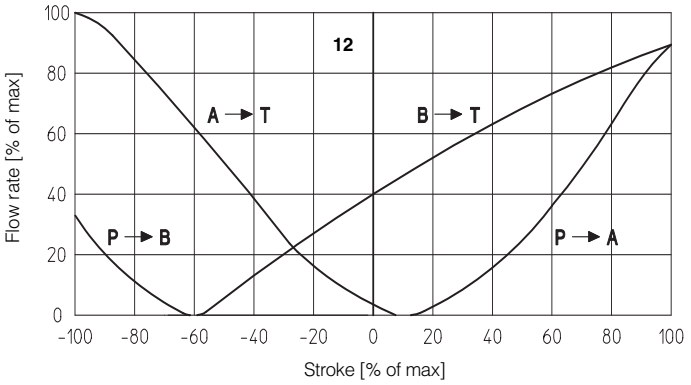
11 = linear spool Q5

Q5 spool type is specific for alternate P/Q controls in combination with /SP option of digital integral drivers, see tab. G212
It allows to control the pressure in A port or B port and it provides a safety central position (A-T/B-T) to depressurize the actuator chambers.
The strong meter-in characteristic makes the spool suitable for both pressure control and motion regulations in several applications.



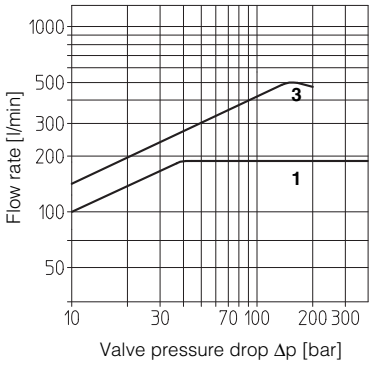
12 = differential - progressive spool V9

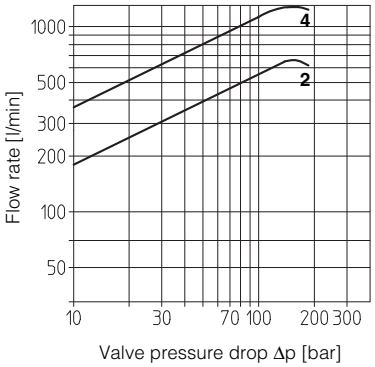
V9 spool type is specific for alternate P/Q controls in combination with /SP option of digital integral drivers, see tab. G212
This spool is specially designed to manage the whole injection cycle in plastic machinery, thanks to the following specific features:
- strong meter-in characteristic to allow the pressure control in A port during the holding pressure (P-A) and the plasticizing (A-T) phases
- safety central position (A-T/B-T) to depressurize the actuator chambers
- large A-T and B-T flow capability, required during the plasticizing phase, to discharge big volumes from high differential injection cylinders with low pressure drops and permitting the contemporary oil suction from tank



13.2 Operating diagrams

Flow /Δp diagram
stated at 100% of spool stroke
DPZO-1:
1 = spools L5, S5, D5, DL5, D9, V9
DPZO-2:
2 = spools L5, S5, D5, DL5, D9, L9, V9
3 = spool L3, S3, D3
DPZO-3:
4 = spools L5, S5, D5, DL5, D9, V9



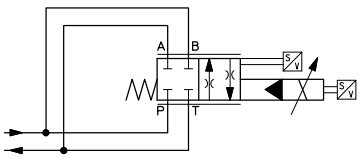


13.3 Dynamic response

The response times in section 3 have to be considered as average values.
For the valves with digital electronics the dynamics performances can be optimized by setting the internal software parameters.

13.4 Operation as throttle valve

Single solenoid valves (*51) can be used as simple throttle valves:
Pmax = 250 bar

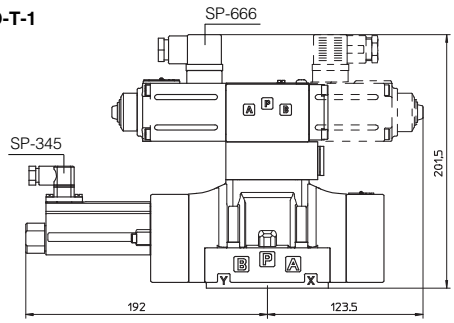


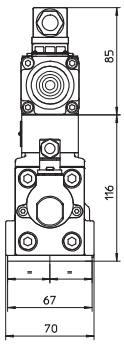
DPZO-*-		151-L5	251-L5	351-L5
Max flow	[l/min]	320	650	1300
Δp	[bar]	30	30	30

14 INSTALLATION DIMENSIONS FOR DPZO-1 AND DPZO-2 [mm]

DPZO-T(*)-1 (dotted line = double solenoid version)

DPZO-T-1



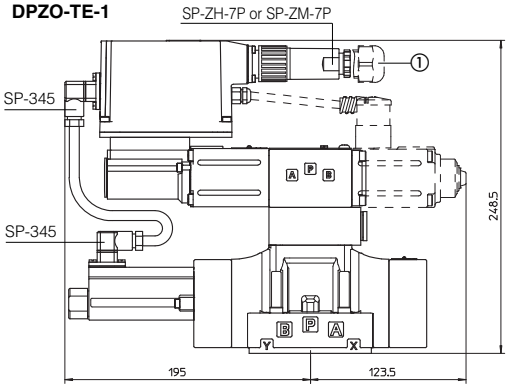


ISO 4401: 2005
Mounting surface: 4401-05-05-0-05 (see table P005)
Fastening bolts:
4 socket head screws M6x40 class 12.9
Tightening torque = 15 Nm
Seals: 5 OR 2050; 2 OR 108
Diameter of ports A, B, P, T: Ø = 11 mm;
Diameter of ports X, Y: Ø = 5 mm;

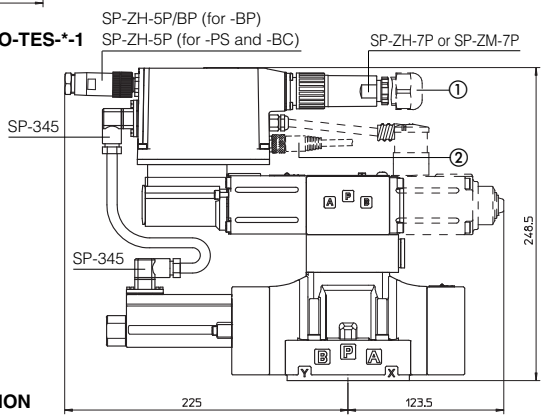
Mass [kg]

	T	TE, TES
DPZO-*-15*	8,5	8,9
DPZO-*-17*	9,4	9,8

DPZO-TE-1



DPZO-TES-*-1



-TE EXECUTION

① = 12 pin connector SP-ZH-12P for option /Z

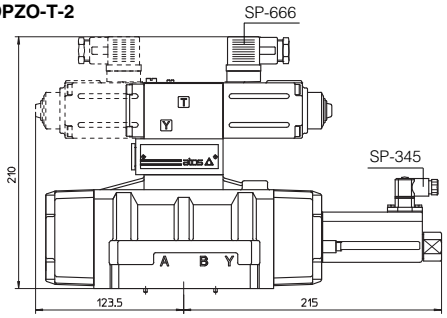
-TES EXECUTION

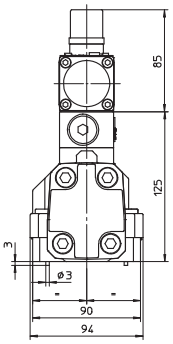
① =12 pin connector SP-ZH-12P for options /SF, /SL, /SP, /Z
② = M8 connector SP-ZH-4P-M8/5 moulded on cable 5 mt lenght for pressure or force transducer (options /SL, /SP)
M8 connector SP-ZH-4P-M8/2-2 moulded with 2 cables, 2 mt lenght for 2 pressure transducers (options /SF)

NOTE:
For option /B the proportional solenoid, the position transducer and the electronics (in case of execution -TE and -TES) are at side of port A of the main stage.

DPZO-T(*)-2 (dotted line = double solenoid version)

DPZO-T-2



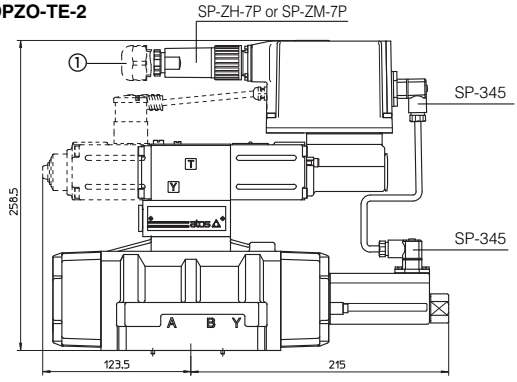


ISO 4401: 2005
Mounting surface: 4401-07-07-0-05 (see table P005)
Fastening bolts:
4 socket head screws M10x50 class 12.9
Tightening torque = 70 Nm
2 socket head screws M6x40 class 12.9
Tightening torque = 15 Nm
Seals: 4 OR 130; 3 OR 109/70
Diameter of ports A, B, P, T: Ø = 20 mm;
Diameter of ports X, Y: Ø = 7 mm;

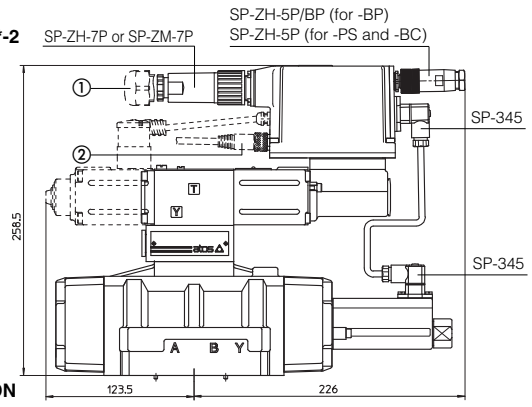
Mass [kg]

	T	TE, TES
DPZO-*-25*	13,5	13,9
DPZO-*-27*	14,4	14,8

DPZO-TE-2



DPZO-TES-*-2



-TE EXECUTION

① = 12 pin connector SP-ZH-12P for option /Z

-TES EXECUTION

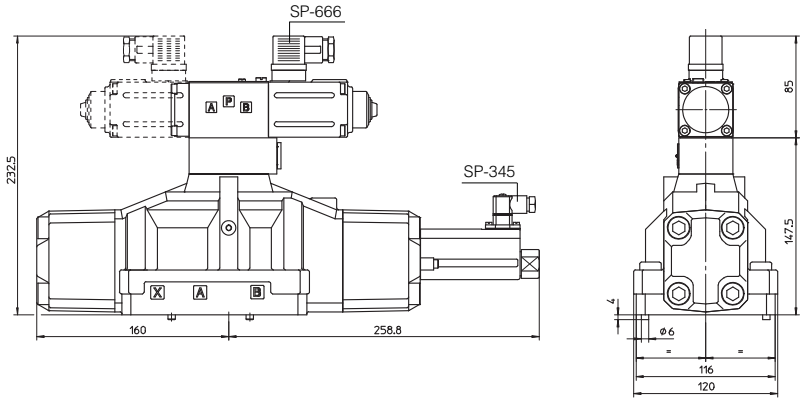
① =12 pin connector SP-ZH-12P for options /SF, /SL, /SP, /Z
② = M8 connector SP-ZH-4P-M8/5 moulded on cable 5 mt lenght for pressure or force transducer (options /SL, /SP)
M8 connector SP-ZH-4P-M8/2-2 moulded with 2 cables, 2 mt lenght for 2 pressure transducers (options /SF)

NOTE:
For option /B the proportional solenoid, the position transducer and the electronics (in case of execution -TE and -TES) are at side of port A of the main stage.

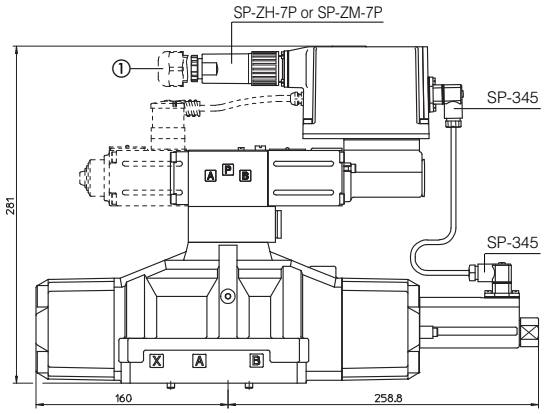
15 INSTALLATION DIMENSIONS FOR DPZO-3 [mm]

DPZO-T(*)-3 (dotted line = double solenoid version)

DPZO-T-3



DPZO-TE-3

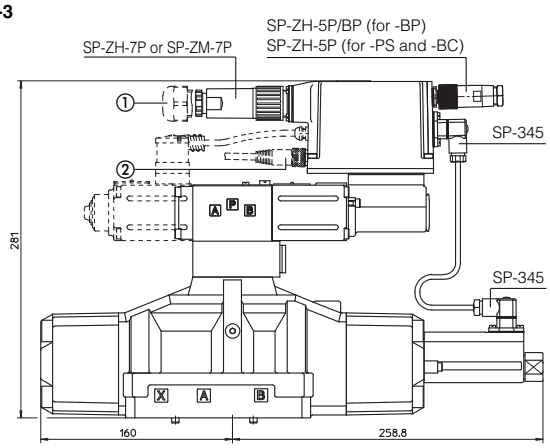


ISO 4401: 2005
Mounting surface: 4401-08-08-0-05 (see table P005)
Fastening bolts:
6 socket head screws M12x50 class 12.9
Tightening torque = 125 Nm
Seals: 4 OR 4112; 3 OR 3056
Diameter of ports A, B, P, T: Ø = 24 mm;
Diameter of ports X, Y: Ø = 7 mm;

-TE EXECUTION

① = 12 pin connector SP-ZH-12P for option /Z

DPZO-TES-*-3



Mass [kg]

	T	TE, TES
DPZO-*-35*	17,1	17,5
DPZO-*-37*	18	18,4

-TES EXECUTION

① =12 pin connector SP-ZH-12P for options /SF, /SL, /SP, /Z
② = M8 connector SP-ZH-4P-M8/5 moulded on cable 5 mt lenght for pressure or force transducer (options /SL, /SP)
M8 connector SP-ZH-4P-M8/2-2 moulded with 2 cables, 2 mt lenght for 2 pressure transducers (options /SF)

NOTE:
For option /B the proportional solenoid, the position transducer and the electronics (in case of execution -TE and -TES) are at side of port A of the main stage.

16 MODEL CODES OF POWER SUPPLY AND COMMUNICATION CONNECTORS (to be ordered separately)

VALVE VERSION	-T		-TE, -TES		-TE/Z -TES /Z, /SF, /SL, /SP	TES -PS, -BC	TES -BP	TES /SF, /SL, /SP
	Power supply	Transducer						
CONNECTOR CODE	SP-666	SP-345	SP-ZH-7P	SP-ZM-7P	SP-ZH-12P	SP-ZH-5P	SP-ZH-5P/BP	SP-ZH-4P-M8/* (1)
PROTECTION DEGREE	IP65	IP65	IP67	IP67	IP65	IP67	IP67	IP67
DATA SHEET	K500		G200, G210, K500			G210, K500		G212, K500

(1) M8 connector SP-ZH-4P-M8/5 moulded on cable 5 mt lenght for pressure or force transducer (options /SL, /SP)
M8 connector SP-ZH-4P-M8/2-2 moulded with 2 cables, 2 mt lenght for 2 pressure transducers (options /SF)

connectors supplied with the valve